MFEM APPLICATION TO EM-WAVE SIMULATION IN ECR SPACE PLASMA THRUSTERS Alvaro Sánchez Villar

Email: asanche2@pppl.gov



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Special acknowledgements to:

Mario Merino, Eduardo Ahedo, Jiewei Zhou & Adrián Dominguez-Vazquez (Universidad Carlos III de Madrid)

Federico Boni, Victor Desangles, Julien Jarrige and Denis Packan (ONERA)

Syun'ichi Shiraiwa and Nicola Bertelli (PPPL)

1. Background

- a. Electric propulsion
- **b.** Electron Cyclotron Resonance Thrusters
- 2. ATHAMES
- 3. Coupled ECRT Simulations
- 4. Validation
- 5. Petra-M preliminary results

6. Conclusions



BACKGROUND

- Electric propulsion (EP)
 - More efficient use of propellant in space compared to chemical propulsion.
 - Most mature electric propulsion technologies (e.g. Hall Effect Thruster, Gridded Ion Thruster) incorporate Erosion — impact on thruster lifetime electrodes:
- Electrodeless plasma thrusters (EPTs)
 - EPTs operation based on radiofrequency coupling :
 - VASIMR
 - Helicon plasma thruster (HPT)
 - Electron Cyclotron Resonance Thruster (ECRT)



HALL EFECT THRUSTER (SEP-NASA)





ECRT OPERATION

- Electron Cyclotron Resonance (ECR):
 - Electrons cyclotron motion resonates with electromagnetic (EM) waves whenever their frequencies match as:

 $\omega_{ce} = \frac{eB}{m_e} = \omega$

- Energized electrons ionize the propellant injected
- Electrons accelerate along the Magnetic nozzle expansion
- An electrostatic potential develops, which accelerates the ions





- Axisymmetric Time HArmonic Maxwell's Equations Solver (ATHAMES)
 - Solves Maxwell's inhomogeneous wave equation in weak form 2D axisymmetric.
 - Finite element method based on a mixed basis formulation.
 - Coded in C++; use of MFEM FE discretization library:
 - Also used by Petra-M analyzing the EM waves in the scrap off layer of a tokamak.
 - Inhomogeneous anisotropic permittivity tensor.
 - Boundary conditions:
 - Perfect electric conductor (PEC).
 - Perfect magnetic conductor (PMC).
 - Symmetry axis.
 - Unstructured grids (GMSH):
 - Complex geometries (e.g., curved).
 - Non-uniform meshes.
 - Predictive mesh refinement.







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Mathematical formulation (weak form) after boundary conditions:

 $\nabla \times \nabla \times \hat{\boldsymbol{E}} - \frac{\omega^2}{c^2} \bar{\bar{\kappa}} \cdot \hat{\boldsymbol{E}} = i\omega\mu_0 \hat{\boldsymbol{j}}_a \longrightarrow \iiint \left[\left(\nabla \times \hat{\boldsymbol{W}}^* \right) \cdot \left(\nabla \times \hat{\boldsymbol{E}} \right) - k_0^2 \left(\bar{\bar{\kappa}} \hat{\boldsymbol{E}} \right) \cdot \hat{\boldsymbol{W}}^* \right] \mathrm{d}V = i\mu_0 \omega \iiint \hat{\boldsymbol{j}}_a \mathrm{d}V.$

- \hat{W} and \hat{E} chosen following Galerkin method.
- Harmonic expansion in azimuthal direction

$$\hat{E}(z,r, heta) = \sum_{m=-\infty}^{\infty} \tilde{E}^{(m)}(z,r)e^{im heta},$$

 $\hat{j}_a(z,r, heta) = \sum_{m=-\infty}^{\infty} \tilde{j}_a^{(m)}(z,r)e^{im heta}.$

Mixed FE discretization

$$\tilde{\boldsymbol{E}}(x_1, x_2) = \sum_i a_i \tilde{N}_i(x_1, x_2) + \sum_l b_l \tilde{L}_l(x_1, x_2) \mathbf{1}_{x_3}$$

- In-plane: Nédélec vector elements (N_i) $ilde{N}_i = l_{ij} \left(\lambda_i
 abla \lambda_j - \lambda_j
 abla \lambda_i
 ight)$
- Out-of-plane: Lagrange nodal elements $~~ ilde{m{L}}_i$
 - Polynomial order p_L





Block matrix assembly (A)

	$ ilde{m{E}}^R_t$	$ ilde{m{E}}^I_t$	$ ilde{E}^R_ heta$	$ ilde{E}^I_ heta$
$ ilde{oldsymbol{W}}_t^R$	$r\left(\nabla \times \tilde{\boldsymbol{W}}_{t}^{R}\right) \cdot \left(\nabla \times \tilde{\boldsymbol{E}}_{t}^{R}\right) \\ -rk_{0}^{2}(\bar{\boldsymbol{\kappa}}_{t,t}^{R} \cdot \tilde{\boldsymbol{E}}_{t}^{R}) \cdot \tilde{\boldsymbol{W}}_{t}^{R} \\ + \frac{m^{2}}{2}\tilde{\boldsymbol{E}}_{t}^{R} \cdot \tilde{\boldsymbol{W}}_{t}^{R}$	$rk_0^2(ar{ar{\kappa}}^I_{t,t}\cdot ilde{m{E}}^I_t)\cdot ilde{m{W}}^R_t$	$-rk_0^2 ilde{E}_{ heta}^R oldsymbol{\kappa}_{t, heta}^R \cdot ilde{oldsymbol{W}}_t^R$	$\begin{split} & -\frac{m}{r} \nabla (r \tilde{E}_{\theta}^{I}) \cdot \tilde{W}_{t}^{R} \\ & + r k_{0}^{2} \tilde{E}_{\theta}^{I} \boldsymbol{\kappa}_{t,\theta}^{I} \cdot \tilde{\boldsymbol{W}}_{t}^{R} \end{split}$
$ ilde{oldsymbol{W}}_t^I$	$-rk_0^2 \left[ar{ar{\kappa}}_{t,t}^I \cdot ilde{m{E}}_t^R ight] \cdot ilde{m{W}}_t^I$	$ \begin{split} r\left(\nabla\times\tilde{\boldsymbol{W}}_{t}^{I}\right)\cdot\left(\nabla\times\tilde{\boldsymbol{E}}_{t}^{I}\right) \\ -rk_{0}^{2}\left[\bar{\boldsymbol{\kappa}}_{t,t}^{R}\cdot\tilde{\boldsymbol{E}}_{t}^{I}\right]\cdot\tilde{\boldsymbol{W}}_{t}^{I} \\ +\frac{m^{2}}{r}\tilde{\boldsymbol{E}}_{t}^{I}\cdot\tilde{\boldsymbol{W}}_{t}^{I} \end{split} $	$\frac{m}{r} \nabla (r \tilde{E}_{\theta}^{R}) \cdot \tilde{W}_{t}^{I} \\ -r k_{0}^{2} \tilde{E}_{\theta}^{R} \boldsymbol{\kappa}_{t,\theta}^{I} \cdot \boldsymbol{\tilde{W}}_{t}^{I}$	$-rk_0^2 ilde{E}_{ heta}^I oldsymbol{\kappa}_{t, heta}^R \cdot ilde{oldsymbol{W}}_t^I$
\tilde{W}^R_θ	$-rk_0^2 ilde{W}^R_{ heta} oldsymbol{\kappa}^R_{ heta,t} \cdot ilde{oldsymbol{E}}^R_t$	$\frac{m}{r} \nabla (r \tilde{W}_{\theta}^{R}) \cdot \tilde{E}_{t}^{I} \\ + r k_{0}^{2} \tilde{W}_{\theta}^{R} \kappa_{\theta,t}^{I} \cdot \tilde{E}_{t}^{I}$	$\frac{1}{r} \nabla (r \tilde{W}_{\theta}^{R}) \cdot \nabla (r \tilde{E}_{\theta}^{R}) \\ -r k_{0}^{2} \kappa_{\theta\theta}^{R} \ \tilde{E}_{\theta}^{R} \tilde{W}_{\theta}^{R}$	$rk_0^2\kappa_{\theta\theta}^I\tilde{E}_{\theta}^I\tilde{W}_{\theta}^R$
\tilde{W}^I_θ	$-\frac{m}{r}\nabla(r\tilde{W}_{\theta}^{I})\cdot\tilde{E}_{t}^{R}\\-rk_{0}^{2}\tilde{W}_{\theta}^{I}\boldsymbol{\kappa}_{\theta,t}^{I}\cdot\tilde{E}_{t}^{R}$	$-rk_0^2 ilde{W}_{ heta}^I oldsymbol{\kappa}_{ heta,t}^R \cdot ilde{oldsymbol{E}}_t^I$	$-rk_0^2\kappa_{\theta,\theta}^I\tilde{E}_\theta^R\tilde{W}_\theta^I$	$ \begin{array}{l} \frac{1}{r} \nabla (r \tilde{W}_{\theta}^{I}) \cdot \nabla (r \tilde{E}_{\theta}^{I}) \\ - r k_{0}^{2} \kappa_{\theta,\theta}^{R} \ \tilde{E}_{\theta}^{I} \tilde{W}_{\theta}^{I} \end{array} $





Axisymmetric boundary conditions

$$\begin{split} E_r^{(0)} &= E_{\theta}^{(0)} = 0 \,, \\ E_r^{(\pm 1)} &= \mp i E_{\theta}^{(\pm 1)} = 0 \,, \quad E_z^{(\pm 1)} = 0 \,, \\ E_r^{(m)} &= E_{\theta}^{(m)} = E_z^{(m)} = 0 \,, \quad |m| > 1 \,. \end{split}$$

Discretization dependent on mode number

$$E^{(m)} = \begin{cases} \sum_{i=1}^{N_{\text{edge}}} N_i(r, z) e_{t,i}^{(m)} + \mathbf{1}_{\theta} \sum_{i=1}^{N_{\text{node}}} N_i(r, z) e_{\theta,i}^{(m)}, & m = 0, \\ \sum_{i=1}^{N_{\text{edge}}} r N_i(r, z) e_{t,i}^{(m)} + (\mathbf{1}_{\theta} \mp i \mathbf{1}_r) \sum_{i=1}^{N_{\text{node}}} N_i(r, z) e_{\theta,i}^{(m)}, & m = \pm 1, \\ \sum_{i=1}^{N_{\text{edge}}} r N_i(z, r) e_{t,i}^{(m)} + \mathbf{1}_{\theta} \sum_{i=1}^{N_{\text{node}}} N_i(z, r) e_{\theta,i}^{(m)}, & |m| > 1. \end{cases}$$

 Combined with PEC boundary conditions on the azimuthal fields at the symmetry axis.





 $\log_{10}(e_t)$ [-Code verification using: The Method of Manufactured solutions Manufactured solution $|\tilde{E}_r^{\rm mms}|$ $= \sin\left(k_1 r\right) + i \sin\left(k_2 r\right) \,,$ $\tilde{E}_z^{\rm mms}$ 1.884 1.5 \boxed{E} 1. 0.9419 0 $= r \left[\sin \left(k_1 z \right) + i \sin \left(k_2 z \right) \right] \,,$ $E^{
m mms}$ $\tilde{E}_{\theta}^{\mathrm{mms}}$ $= \sin\left(k_1 r\right) + i \sin\left(k_2 r\right) \,.$ 0.0-z [m $\log_{10}(h)$ $\nabla \times \nabla \times \tilde{E}^{\text{mms}} - \frac{\omega^2}{c^2} \bar{\kappa} \cdot \tilde{E}^{\text{mms}} = i\omega\mu_0 \tilde{j}_a^{\text{mms}}$ $ightarrow \widetilde{m{j}}_a^{
m mms}$ $\log_{10}(e_{\theta})$ [$ilde{E}$ -**ATHAMES** $e = \int_{\Sigma} \| \tilde{E} - \tilde{E}^{\text{mms}} \|_2 d\Sigma$ Error convergence agreement with FE order used • Tangential fields (vector) order 2 Azimuthal fields (nodal) order 3



 $\log_{10}(h)$

- Predictive mesh refinement
 - Fast oscillations in specific CMA regions
 - Similar oscillations observed in other research for the lower hybrid resonance (LHR) in the context of fusion.
 - Spurious character since fast oscillations wavelength is much smaller tan physical, and in the order of the mesh characteristic length.
 - Predictive refinement allows to mitigate these oscillations from the solution.



October 25, 2022

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COUPLED ECRT SIMULATION

PLASMA TRANSPORT



ELECTROMAGNETIC RESPONSE





A. Sánchez-Villar, J. Zhou, E. Ahedo, and M. Merino. Coupled plasma transport and electromagnetic wave simulation of an ECR thruster. *Plasma Sources Science and Technology 30 (2021) 045005*.

October 25, 2022

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COMPARISON TO EXPERIMENTS

MFEM Workshop 2022 - Alvaro Sánchez Villar

THE FRENCH AEROSPACE LAB

- Validation campaign carried out at ONERA facilities
- Dielectric-coated ECRT

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COMPARISON TO EXPERIMENTS

Good agreement with experimental results along the magnetic nozzle
 ANGULAR
 AXIAL

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and Technology (2022).

Petra-M Simulations

• Petra-M: 3D + HPC capabilities

 Preliminary E-field solution with uniform tetrahedral mesh, ND elements order 2. Further refinement required in resonances.

 Predictive mesh refinement based on estimated characteristic wavelengths depending on EM plasma regions

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CONCLUSIONS

- Direct application of MFEM to the modeling of space plasma thrusters.
- 2D axisymmetric electromagnetic simulation code based on mixed finite elements
 - capable of solving the electromagnetic wave propagation and absorption in ECRT plasmas
 - Predictive mesh refinement based on the plasma and magnetic properties.
- Allowed to obtain:
 - First coupled simulations of an ECRT by coupling plasma transport and electromagnetic problems.
 - First validation of the model against experiments of benchmark ECRT prototype at ONERA
 - Good agreement between simulations and experiments and also to identify potential model improvements.
- Petra-M allows for the obtention of solutions efficiently and with 3D capabilities, crucial for non-axisymmetric thruster configurations.

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THANK YOU!

Magnetic nozzle thruster with electron cyclotron resonance